

ROPE RESCUE TECHNICIAN

WWW.KCTR1.ORG

SITE OPERATION

Evaluation Sheet: RT-1

Student:		Date	2:		
	Dept:				
	ARD: Ch. 5 1006, 2013 Edition	TASK: Identification of site control objectives			
Perfoi	RMANCE OUTCOME: Identify site c	ontrol objectives			
CONDI	TIONS: Given a scenario, the candid	late shall demonstrate the ability to:			
No.	TASK STEPS		OK	N/A	
1.	Identify needed support resources (5.2.1)				
2.	Perform a rope rescue incident size-up (5.2.2)				
3.	Identify and manage incident hazards (5.2.3)				
4.	Manage resources in a rescue incident (5.2.4)				
5.	Conduct a search (5.2.5)				
6.	Terminate an incident (5.2.7)				
7.	Ensure safety practices (5.5.12)				
	•				

Evaluator

Date

Candidate



ROPE RESCUE TECHNICIAN

WWW.KCTR1.ORG

ROPES/RIGGING/PPE

Evaluation Sheet: RT-2

Student:		I	Date:				
	Dept:						
STANDARD: Ch. 5 NFPA 1006, 2013 Edition		TASK: Demonstration and instruction of ropes, rope equipment, and PPE					
Perfo	RMANCE OUTCOME: Identify rope	s, rope equipment, PPE, and tie knots.					
Condi	TIONS: Given rope, rope equipmen	t, and PPE, the candidate shall demonstrate the	ability to:				
No.	TASK STEPS			N/A			
1.	Identify rescue ropes, inspection requirements, and care techniques (5.4.2)						
2.	Identify rope equipment and define uses (5.4.1)						
3.	Tie rope rescue knots (5.5.1)						
4.	Identify PPE for rope rescue (5.4.1)						
5.	Construct single point anchors and anchor systems (5.5.2)						
6.	Construct and operate a belay (5.5.9), (5.5.10)						
7.	Belay a falling load (5.5.11)						
8.	Ensure safety practices (5.5.12)						
			W				

Evaluator

Date

Candidate



ZONE

ROPE RESCUE TECHNICIAN

WWW.KCTR1.ORG

LOW ANGLE SYSTEMS

Evaluation Sheet: RT-3

Student:		Date	:					
	Dept:							
STANDARD: Ch. 5, 6TASK: Demonstration and instructionNFPA 1006, 2013 EditionTask: Demonstration and instruction				e rope sys	stems			
Perfoi	RMANCE OUTCOME: Construct lov	v-angle rope rescue syste	ms					
Condi	FIONS: Given rope and rope equipr	nent, the candidate shall	demonstrate the ability to:					
No.	TASK STEPS							
1101		TASK OTELS		OK	NA			
1.	Construct a low-angle rope rescue system (5.5.4 through 5.5.8)							
2.	Demonstrate patient lashing for a	rescue (6.1.A)						
3.	Demonstrate low-angle litter carrying techniques (5.5.6), (5.3.2)							
4.	Ensure safety practices (5.5.12)							
	·							

Evaluator

Date

Candidate

ROPE RESCUE TECHNICIAN

WWW.KCTR1.ORG

HIGH-ANGLE SYSTEMS: FIXED ROPE ASCENDING/DESCENDING **Evaluation Sheet: RT-4** Student: Date: Dept: STANDARD: Ch. 5, 6 TASK: Demonstration and instruction fixed rope systems for ascending NFPA 1006, 2013 Edition PERFORMANCE OUTCOME: Construct a fixed rope rescue systems, ascending with mechanical ascenders and Purcell prusiks CONDITIONS: Given rope and rope equipment, the candidate shall demonstrate the ability to: No. TASK STEPS OK NA Construct a fixed rope system (6.1.5) 1. 2. Ascend a fixed rope system (6.1.7) 3. Descend a fixed rope system (6.1.8) 4. Lead climb in a high angle environment (6.2.7) 5. Ensure safety practices (5.5.12)

Evaluator

Date

Candidate



ROPE RESCUE TECHNICIAN

WWW.KCTR1.ORG

ອມ	udent:	Da	te:		
	Dent:				
	ARD: Ch. 5, 6 1006, 2013 Edition	TASK: Demonstration and instruction of high-a	ngle rope sy	/stems: pick-o	ffs
Perfo	RMANCE OUTCOME: Constru	uct a high-angle raising/lowering system, perform pick-o	offs		
Condi	TIONS: Given rope and rope	equipment, the candidate shall demonstrate the ability to	:		
No.		TASK STEPS	ОК	NA	
1.	Construct a high-angle raisi	ng/lowering system (6.1.1, 6.1.2)			
2.	Construct a multi-point and	thor system (6.1.3)			
3.	Construct and operate a con	mpound mechanical advantage system (6.1.4, 6.1.6)			
4.	Perform victim pick-off (6.2	Perform victim pick-off (6.2.4)			
	Complete assignment while	suspended (6.2.1)			
5.	1 0			1	

Evaluator

Date

Candidate



ROPE RESCUE TECHNICIAN

WWW.KCTR1.ORG

HIGH-ANGLE SYSTEMS: TENDED LITTER

Evaluation Sheet: RT-6

Student:		D	ate:			
	Dept:					
	ARD: Ch. 5, 6 1006, 2013 Edition	TASK: Demonstration and instruction of litter	management	techniqu	es	
PERFO	RMANCE OUTCOME: Manage lit	tter in a high-angle rope rescue system				
Condi	TIONS: Given rope, rope equipm	ent, and a litter, the candidate shall demonstrate the	e ability to:			
No.		ОК	NA			
1.	Construct a high-angle rope res					
2.	Construct a multi-point anchor system (6.1.3)					
3.	Rig litter for high angle environ	nment (6.1.B)				
4.	Construct and operate a compound mechanical advantage system (6.1.4, 6.1.6)					
5.	Demonstrate victim packaging for a litter (6.1.A)					
6.	Perform as a litter tender in a high angle environment (6.2.3)					
7.	Complete assignment while suspended (6.2.1)					
8.	Ensure safety practices (5.5.12)					
	•					

Evaluator

Date

Candidate



ROPE RESCUE TECHNICIAN

WWW.KCTR1.ORG

GUIDING LINE SYSTEMS

Evaluation Sheet: RT-7

Student:			Date	:		
	Dept:					
STANDARD: Ch. 5, 6 NFPA 1006, 2013 Edition TASK: Demonstration			n and instruction of guiding l	ine rope s	systems	
Perfoi	RMANCE OUTCOME: Construct gui	ding line rope rescue sy	ystems			
CONDIT	TIONS: Given rope and rope equipr	nent, the candidate shal	l demonstrate the ability to:			
No.	TASK STEPS				NA	
1.	Construct and operate a guiding line rope rescue system (6.2.5, 6.2.6)			OK	1 11 1	
2.	Demonstrate passing knots through a rope rescue system					
3.	Ensure safety practices (5.5.12)					

Evaluator

Date

Candidate